



Sensitivity analysis for optimization  
under constraints and with uncertainties  
Kernel-based Sensitivity Analysis on (excursion) sets

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Journées CIROQUO, 23-35 may 2023



# From a complex system to robust optimization

Input parameters :

- component size
- material
- swell height
- ...

inputs

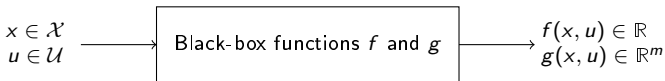
Complex system :  
Floating wind turbine

output

- Cost
- energy production
- environmental impact
- ...



# From a complex system to robust optimization



- The  $x$  are the deterministic inputs
- The  $u$  are uncertain inputs :  $u = U(\omega)$  with  $U$  a random vector of density  $\mathbb{P}_U$
- $f$  is the objective function to minimize
- $g$  is the constraint function defining the constraint to respect :  $g \leq 0$

## Robust optimization problem

$$x^* = \arg \min_{x \in \mathcal{X}} \mathbb{E}[f(x, U)] \text{ s.t. } \mathbb{P}[g(x, U) \leq 0] \geq P_{\text{target}}$$

**How can Sensitivity Analysis be used to reduce the cost of a robust optimization ?**

# Robust Optimization and sensitivity analysis

Robust optimization problem...

$$x^* = \arg \min_{x \in \mathcal{X}} \mathbb{E}[f(x, U)] \text{ s.t. } \mathbb{P}[g(x, U) \leq 0] \geq P_{\text{target}}$$

... seen without the  $U$

$$x^* = \arg \min_{x \in \mathcal{X}} F(x) \text{ s.t. } G(x) \leq 0$$

- Goal Oriented Sensitivity Analysis to reduce the input dimension : Spagnol 2020
- Huge evaluation cost of  $F$  and  $G$
- What about the  $U$ ?

**How to quantify the impact of the uncertain inputs  $U$  on the optimization ?**

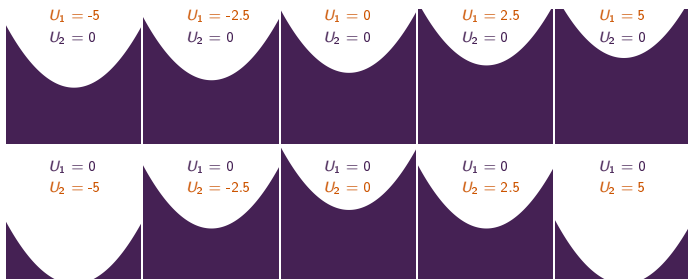
→ SA on excursion sets :  $U \xrightarrow{\phi} \Gamma = \{x \in \mathcal{X}, g(x, U) \leq 0\}$

## A toy excursion set

Toy function from [El-Amri et al. 2021]

$$\forall (x, u) \in [-5, 5]^4 \quad g(x, u) = -x_1^2 + 5x_2 - u_1 + u_2^2 - 1$$

$$\Gamma_u = \{x \in [-5, 5]^2, g(x, u) \leq 0\}$$



# SA on excursion sets

## Excursion sets

New output :

$$\Gamma_U = \{x \in \mathcal{X}, g(x, U) \leq 0\}, \quad (1)$$

which is called a random excursion set.

Influence of the uncertain inputs  $U$  on  $\Gamma_U$ ?  $\Rightarrow$  SA on excursion sets.

Yet most SA techniques have scalar or vectorial outputs.

**How then can we do sensitivity analysis on (excursion) sets?**

– SA on sets using random set theory notably

Vorob'ev expectation and deviation

– SA on sets using universal indices

from Fort, Klein et Lagnoux 2021

– **SA on sets using RKHS theory :**

→ one article (pre-print on HAL)

} One applicative article planned

# Table of Contents

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  - Distribution embedding into a RKHS
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- 2 Kernel-based Sensitivity Analysis on sets
  - A kernel between sets
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  - Toy excursion set
  - Pollutant concentration maps



# Table of Contents

- 1 Kernel-based Sensitivity Analysis
  - Distribution embedding into a RKHS
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# Distribution embedding into a RKHS

Dependence measures :  $S_i = \|\mathbb{P}_{(X_i, Y)} - \mathbb{P}_{X_i} \otimes \mathbb{P}_Y\|$

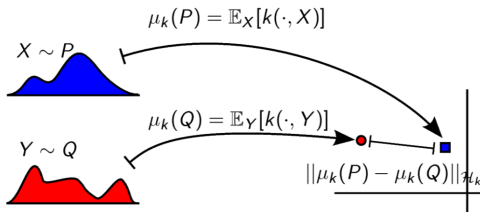


Figure – Kernel mean embedding

with  $k$  a (positive definite) kernel  $k : (x, x') \in \mathcal{X}^2 \mapsto k(x, x') \in \mathbb{R}$ .

Hilbert Schmidt Independence Criterion (HSIC), Gretton et al. 2006

With  $K = k_{X_i} \otimes k_Y$ , the HSIC is given by :

$$\text{HSIC}_K(X_i, Y) = \|\mu_K(X_i, Y) - \mu_{k_{X_i}}(X_i) \otimes \mu_{k_Y}(Y)\|_{\mathcal{H}_K}^2$$

When  $K$  is **characteristic** (injectivity of the mean embedding),

$$\text{HSIC}_K(X_i, Y) = 0 \text{ iff } X_i \perp Y \rightarrow \text{screening.}$$

## HSIC-ANOVA index [daVeiga 2021]

Assuming that the inputs are **independent** and that the input kernels are **ANOVA**,

$$\text{HSIC}(\mathbf{X}, Y) = \sum_{A \subseteq \{1, \dots, d\}} \sum_{B \subseteq A} (-1)^{|A|-|B|} \text{HSIC}(\mathbf{X}_B, Y).$$

HSIC-ANOVA indices are then defined as :

$$S_i^{\text{HSIC}} := \frac{\text{HSIC}(X_i, Y)}{\text{HSIC}(\mathbf{X}, Y)},$$

$$S_{T_i}^{\text{HSIC}} := 1 - \frac{\text{HSIC}(\mathbf{X}_{-i}, Y)}{\text{HSIC}(\mathbf{X}, Y)}$$

and are suited for **ranking** (and screening).

- Easy to estimate :

$$\begin{aligned} \text{HSIC}_{k_{\mathcal{X}}, k_{\mathcal{Y}}}(X, Y) &= \mathbb{E}[k_{\mathcal{X}}(X, X')k_{\mathcal{Y}}(Y, Y')] \\ &\quad + \mathbb{E}[k_{\mathcal{X}}(X, X')]\mathbb{E}[k_{\mathcal{Y}}(Y, Y')] \\ &\quad - 2\mathbb{E}[\mathbb{E}[k_{\mathcal{X}}(X, X')|X]\mathbb{E}[k_{\mathcal{Y}}(Y, Y')|Y]]. \end{aligned}$$

- Only requirement : to have kernels on the inputs and on the output

# Table of Contents

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## SA on sets : a kernel between sets

With  $A\Delta B = A \cup B - B \cap A$  and  $\lambda$  the Lebesgue measure, we define a kernel on the Lebesgue  $\sigma$ -algebra  $\mathcal{B}(\mathcal{X})$  by :

$$\forall \Gamma_1, \Gamma_2 \in \mathcal{B}(\mathcal{X}), k_{\text{set}}(\Gamma_1, \Gamma_2) = \exp\left(-\frac{\lambda(\Gamma_1\Delta\Gamma_2)}{2\sigma^2}\right).$$

Proposition (A kernel between sets)

$k_{\text{set}}$  is a kernel [Balança et Herbin 2012] and is characteristic.

$k_{\text{set}}$  is characteristic, sketch of proof

- $\mathcal{B}(\mathcal{X}) \rightarrow \mathcal{B} = \mathcal{B}(\mathcal{X}) / \sim_\delta$  where  $\delta$  is the volume of the symmetric difference and  $\sim_\delta$  the equivalent relation  $A \sim_\delta B$  iff  $\delta(A, B) = 0$  i.e.  $A$  and  $B$  are equal except on a  $\lambda$ -negligible set.
- We show that  $(\mathcal{B}, \delta)$  is a Polish space (separable completely metrizable topological space).  $(\mathcal{B}, \delta)$  is a metric space so we just need separability and completeness. Separability holds as "it's a subspace of  $L_2(\mathcal{X})$ " and we show that it's closed.
- We use a Proposition from Ziegel, Ginsbourger et Dümbgen 2022,

## Proposition

Let  $\mathcal{B}$  be a Polish space,  $H$  a separable Hilbert space,  $T$  a measurable and injective mapping from  $\mathcal{B}$  to  $H$ , and  $\varphi \in \Phi_\infty^+$ . Then, the kernel  $k$  on  $\mathcal{B}$  defined by

$$k(\gamma, \gamma') := \varphi \left( \|T(\gamma) - T(\gamma')\|_H^2 \right), \quad \gamma, \gamma' \in \mathcal{B}$$

is integrally strictly positive definite with respect to  $\mathcal{M}(\mathcal{B})$  (which implies that it is characteristic).

with  $H = L_2(\mathcal{X})$ ,  $\varphi = \exp(-\frac{\cdot}{2\sigma^2})$  and  $T$  defined by  $T(\gamma) := x \mapsto \mathbb{1}_\gamma(x)$  for any  $\gamma \in \mathcal{B}$  so that  $\|T(\gamma) - T(\gamma')\|_H^2 = \lambda(\gamma \Delta \gamma')$ .

## HSIC-ANOVA on sets, estimation

- $H_{\text{set}}(U_I, \Gamma) := \text{HSIC}_{k_I, k_{\text{set}}}(U_I, \Gamma) = \mathbb{E}[(k_I(U_I, U_I') - 1)k_{\text{set}}(\Gamma, \Gamma')]$

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- $\widehat{H}_{\text{set}}(U_I, \Gamma) = \frac{2}{n(n-1)} \sum_{i < j}^n (k_I(U_I^{(i)}, U_I^{(j)}) - 1) k_{\text{set}}(\Gamma^{(i)}, \Gamma^{(j)})$



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- $\widehat{k}_{\text{set}}(\Gamma^{(i)}, \Gamma^{(j)}) = \exp\left(-\frac{\lambda(\mathcal{X})}{2\sigma^2} \frac{1}{m} \sum_{k=1}^m \mathbb{1}_{\Gamma^{(i)} \Delta \Gamma^{(j)}}(X_{i,j}^{(k)})\right) \rightarrow n(n-1)m \text{ tests of } X \in \Gamma$

## HSIC-ANOVA on sets, estimation

- $H_{set}(U_I, \Gamma) := \text{HSIC}_{k_I, k_{set}}(U_I, \Gamma) = \mathbb{E}[(k_I(U_I, U_I') - 1)k_{set}(\Gamma, \Gamma')]$
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## Proposition

The quadratic risk of the nested estimator  $\widehat{H}_{\text{set}}$  verifies :

$$\mathbb{E} \left( \widehat{H}_{\text{set}}(U_I, \Gamma) - H_{\text{set}}(U_I, \Gamma) \right)^2 \leq 2 \left( \frac{2\sigma_1^2}{n(n-1)} + \frac{4(n-2)\sigma_2^2}{n(n-1)} + \frac{L^2\sigma_3^2}{m} \right).$$

## HSIC-ANOVA on sets, estimation

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We can now compute  $S_i^{\widehat{\widehat{H}}_{\text{set}}}$  or  $S_{T_i}^{\widehat{\widehat{H}}_{\text{set}}}$  to perform SA on set-valued outputs.

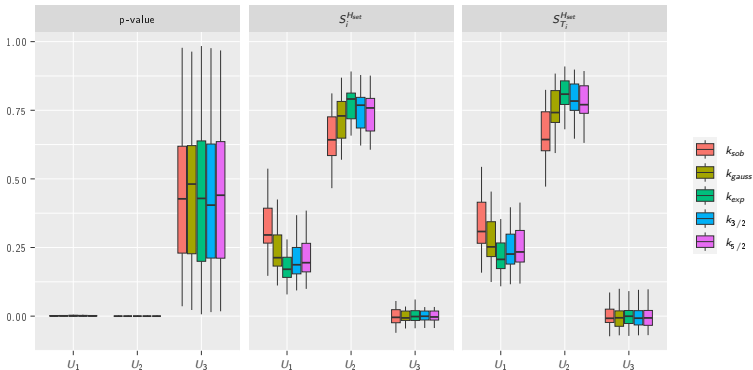
# Table of Contents

- 1 Kernel-based Sensitivity Analysis
  - Distribution embedding into a RKHS
  - From a distance between distributions to sensitivity indices
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# Toy function 1

From El-Amri et al. 2021,

$$\forall x, u \in [-5, 5]^2 \times [-5, 5]^3 \quad g(x_1, x_2, u_1, u_2, u_3) = -x_1^2 + 5x_2 - u_1 + u_2^2 - 1$$



**Figure** – Estimation of the p-values,  $\hat{S}_i^{Hset}$  and  $\hat{S}_{T_i}^{Hset}$  for the excursion set defined by the constraint  $g \leq 0$  computed for 5 input kernels with  $n = 100$ ,  $m = 100$  and repeated 20 times

# Toy function 1, quadratic risk

## Proposition

The quadratic risk of the nested estimator  $\widehat{\widehat{H}}_{set}$  verifies :

$$\mathbb{E} \left( \widehat{\widehat{H}}_{set}(U_I, \Gamma) - H_{set}(U_I, \Gamma) \right)^2 \leq 2 \left( \frac{2\sigma_1^2}{n(n-1)} + \frac{4(n-2)\sigma_2^2}{n(n-1)} + \frac{L^2\sigma_3^2}{m} \right).$$

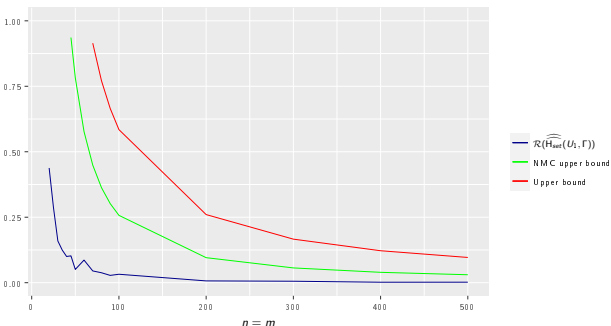
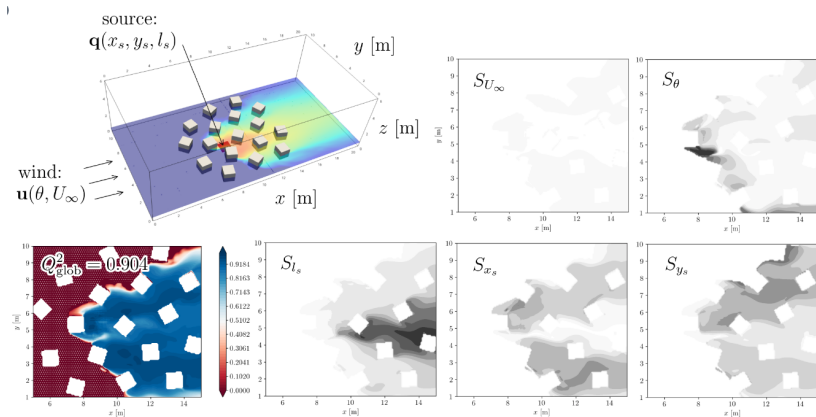


Figure – Evolution of  $\mathcal{R}(\widehat{\widehat{H}}_{set}(U_1, \Gamma))$  and of the associated upper bounds for the excursion set of the constraint  $g \leq 0$



# Pollutant concentration maps : Maps of Sobol indices



Interpretation :

$$S_{l_s} \gg S_{x_s} \approx S_{y_s} \approx S_\theta \gg S_{U_\infty}$$

## Kernel-based SA on pollutant concentration maps

Sobol map interpretation :  $S_{I_s} \gg S_{x_s} \approx S_{y_s} \approx S_\theta \gg S_{U_\infty}$ .

$\forall (x, y) \in [5, 15] \times [1, 10]$ ,  $g(x, y, U)$  is the pollutant concentration at the point  $(x, y)$  for a given uncertain parameter  $U$ . What is the set-valued output ?

- Test 1 :  $\Gamma_U = \{(x, y) \in [5, 15] \times [1, 10], g(x, y, U) \geq C_{seuil}\}$ .  $C_{seuil}$  to choose (toxicity threshold).

	$\theta$	$U_\infty$	$x_s$	$y_s$	$I_s$
P-value	$6.6 \cdot 10^{-4}$	0.11	0	0	0
$S_i^{Hset}$	0.069	0.016	0.25	0.15	0.48

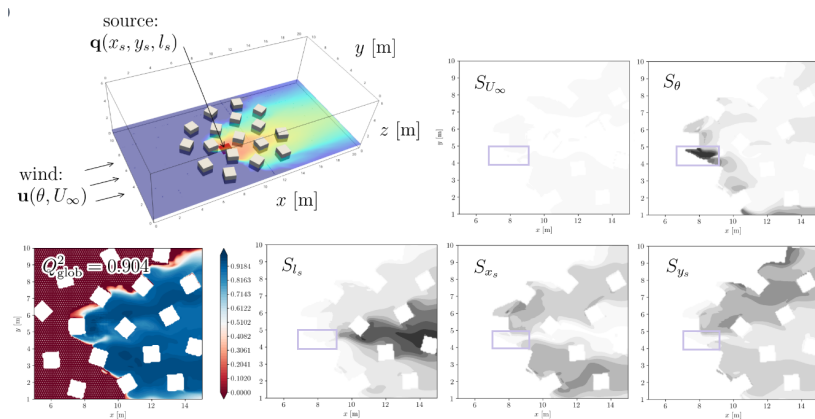
- Test 2 :  $\Gamma_U = \{(x, y, z) \in [5, 15] \times [1, 10] \times [C_{min}, C_{max}], z \leq g(x, y, U)\}$

	$\theta$	$U_\infty$	$x_s$	$y_s$	$I_s$
P-value	$6.6 \cdot 10^{-3}$	0.77	0.026	0.010	0
$S_i^{Hset}$	0.11	0.0081	0.20	0.17	0.50

In both cases we obtain :

$$S_{I_s} > S_{x_s} > S_{y_s} > S_\theta > S_{U_\infty}$$

## Kernel-based SA on pollutant concentration maps : subspace






$$\Gamma_U = \{(x, y, C) \in [7, 9] \times [4, 5] \times [C_{\min}, C_{\max}], C \leq g(x, y, U)\}$$

	$\theta$	$U_\infty$	$x_s$	$y_s$	$l_s$
P-value	0	0.002	0	0	0.03
$S_i^{\text{H}_{\text{set}}}$	0.59	0.09	0.14	0.13	0.04

# Outlook of the thesis

- Does this work in high dimensional space  $\mathcal{X}$ ?
  - Very small volumes? → importance sampling?
  - If we know that the "effective" dimension  $d'$  of  $\Gamma_U$  is small, can we still conduct the sensitivity analysis on  $\mathcal{X}$  or should we reduce the dimension on the  $x$  before?
- How / where to use a sensitivity analysis on the  $U$  (and on the  $x$ ) inside a robust optimization methodology?

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